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**AMENDMENTS TO THE CLAIMS**

This listing of claims will replace all prior versions, and listings, of claims in the application:

**Listing of Claims**

Please cancel claims 1-17.

Please add new claims 18-37 as follows:

18. (New) A drive mechanism for a body, wherein said body has a plurality of load bearing track engaging wheels that allow said body to move back and forth along a track, said drive mechanism comprising:

an actuator attached to said body that is driven,

a non-load bearing drive wheel that is attached with respect to said body so that it engages a stationary surface adjacent said body, said drive wheel and said actuator located on the same side of said track, and

a drive coupling means between said actuator and said drive wheel wherein actuation of said actuator causes rotation of said drive wheel which moves said body along said tracks.

19. (New) The drive mechanism according to claim 18, wherein said drive wheel frictionally engages said surface.

20. (New) The drive mechanism according to claim 19, wherein the periphery of said drive wheel comprises a material having a high friction co-efficient.

21. (New) The drive mechanism according to claim 20, wherein said material comprises polyurethane.

22. (New) The drive mechanism according to claim 18, further comprising a means of biasing said drive wheel towards said surface.

23. (New) The drive mechanism according to claim 22, wherein said biasing means comprises a carriage to which said drive wheel is mounted that is pivotally mounted with respect to said body and a spring mounted between said carriage and said body that urges said carriage towards said surface.

24. (New) The drive mechanism according to claim 18, further comprising reduction gearing between said actuator and said drive wheel.

25. (New) The drive mechanism according to claim 18, wherein said drive coupling comprises a belt extending between said actuator and said drive wheel.

26. (New) The drive mechanism according to claim 25, further comprising an intermediate pair of pulleys with said belt extending to a first of said pulleys with a second belt extending from a second of said pulleys to said drive wheel.

27. (New) The drive mechanism according to claim 18, wherein said actuator comprises a manually operated crank.

28. (New) The drive mechanism according to claim 27, wherein said crank comprises a wheel.

29. (New) A drive mechanism for a body, wherein said body has a plurality of load bearing track engaging wheels that allow said body to move back and forth along a track, said drive mechanism comprising:

a non-load bearing drive wheel that is attached with respect to said body so that it frictionally engages a stationary surface adjacent said body, and

drive means for rotating said drive wheel to move said body along said tracks, wherein said drive means and said drive wheel are located on the same side of said track.

30. (New) A plurality of track mounted cabinets using a drive mechanism according to claim 18, wherein each said cabinet comprises a body with said drive mechanism attached to each said cabinet.

31. (New) The track mounted cabinets according to claim 30, wherein said surface is an elongate track extending along the length of said cabinets that is engaged by said drive wheel.

32. (New) The track mounted cabinets according to claim 31, wherein said elongate track is attached to any one of said tracks supporting said cabinets.

33. (New) A plurality of track mounted cabinets using a drive mechanism according to claim 29, wherein each said cabinet comprises a body with said drive mechanism attached to each said cabinet.

34. (New) The track mounted cabinets according to claim 33, wherein said surface is an elongate track extending along the length of said cabinets that is engaged by said drive wheel.

35. (New) The track mounted cabinets according to claim 34, wherein said elongate track is attached to any one of said tracks supporting said cabinets.

36. (New) The drive mechanism according to claim 18, wherein said actuator is manually driven

37. (New) The drive mechanism according to claim 36, wherein said actuator is mechanically driven.